

**Seventh Semester B.E. Degree Examination, Dec.2017/Jan.2018**  
**Control Engineering**

Time: 3 hrs.

Max. Marks: 100

**Note: Answer any FIVE full questions, selecting atleast TWO questions from each part.**

**PART - A**

- 1 a. Define a system, control, plant, controller and disturbance. (05 Marks)  
 b. Give the requirements of an ideal control system. (05 Marks)  
 c. Describe about the Proportional + Integral controller and proportional + Integral + Derivative controller with suitable diagrams. (10 Marks)
  
- 2 a. Write down the steps to solve problems on Analogous (F – V, F – I) systems. (08 Marks)  
 b. Draw the equivalent mechanical system and analogous systems based on F-V, F-I methods for the given system. (12 Marks)

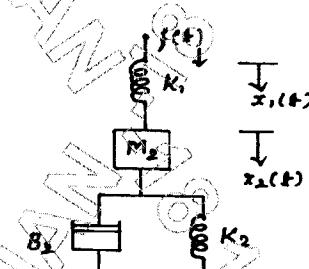


Fig.Q2(b)

- 3 a. Determine the overall transfer function  $C(s)/R(s)$  for the system shown in the Fig.Q3(a). (10 Marks)

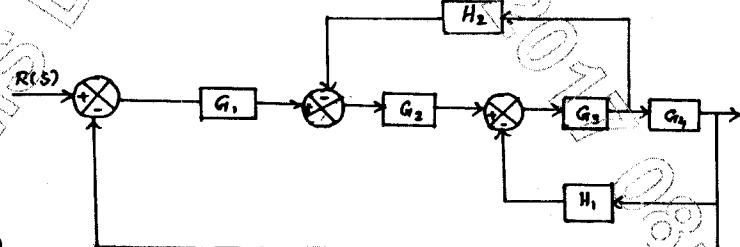


Fig.Q3(a)

- b. Find the overall gain  $C(s)/R(s)$  for the signal flow graph shown in the following Fig.Q3(b). (10 Marks)

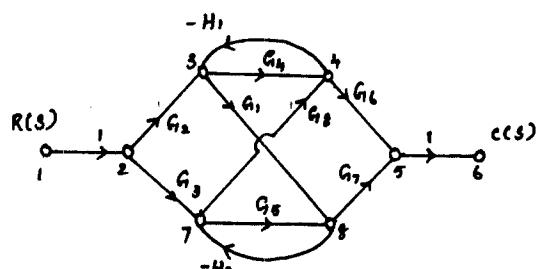


Fig.Q3(b)

- 4 a. Check the stability of the given characteristic equation using Routh's method  
 $s^6 + 4s^5 + 3s^4 - 16s^2 - 64s - 48 = 0$  (10 Marks)
- b. Derive the expression for unit step response of underdamped second order system. (10 Marks)

**PART – B**

- 5 a. Sketch the polar plot and determine the gain margin and phase margin for the open loop transfer function is given by  $G(s) = \frac{1}{s(s+1)(1+2s)}$ . (12 Marks)
- b. Write down the steps to solve problems by Nyquist criterion. (08 Marks)
- 6 Sketch Bode plot for the following transfer function and determine the system gain K for the gain cross over frequency to be 5 rad/sec.

$$G(s) = \frac{Ks^2}{(1+0.2s)(1+0.02s)} \quad (20 \text{ Marks})$$

- 7 a. Describe the steps for constructing the root locus. (08 Marks)
- b. Sketch the root locus of system having,  $G(s)H(s) = \frac{K}{s(s+3)(s+5)}$ . (12 Marks)
- 8 a. What is compensation? Describe about the lead compensator and its steps for designing. (10 Marks)
- b. Give explanation about lag-lead compensation with relevant diagrams. (10 Marks)

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